

Sparse Fourier Transform (lecture 1)

Michael Kapralov¹

¹IBM Watson

MADALGO'15

Given $x \in \mathbb{C}^n$, compute the Discrete Fourier Transform (DFT) of x :

$$\hat{x}_i = \frac{1}{n} \sum_{j \in [n]} x_j \cdot \omega^{-ij},$$

where $\omega = e^{2\pi i/n}$ is the n -th root of unity.

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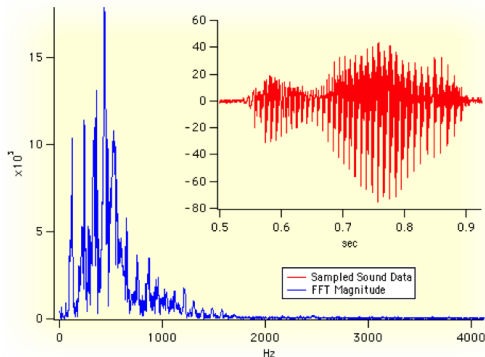
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**compression schemes
(JPEG, MPEG)
signal processing
data analysis
imaging (MRI, NMR)**

DFT has numerous applications:



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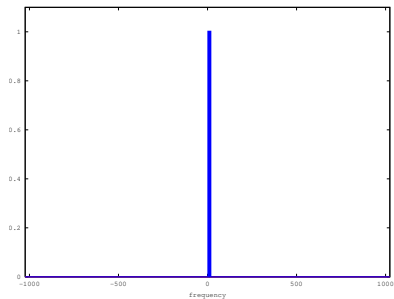
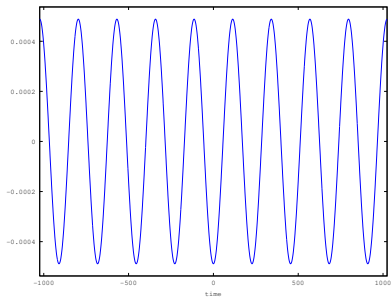
Gauss, 1805



Code=FFTW (Fastest Fourier Transform in the West)

Sparse FFT

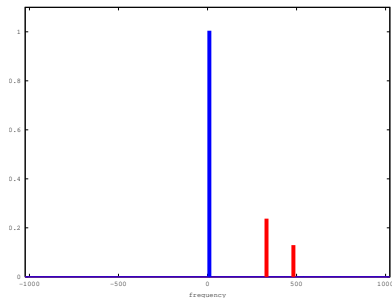
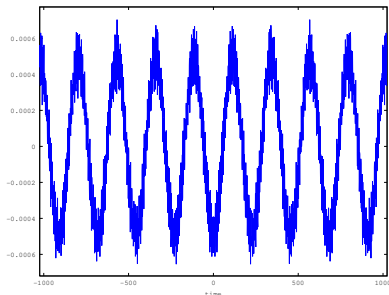
Say that \hat{x} is *k-sparse* if \hat{x} has k nonzero entries



Sparse FFT

Say that \hat{x} is *k-sparse* if \hat{x} has k nonzero entries

Say that \hat{x} is *approximately k-sparse* if \hat{x} is close to k -sparse in some norm (ℓ_2 for this lecture)



Sparse approximations



Given x , compute \hat{x} , then keep **top k coefficients only** for $k \ll N$

Used in image and video compression schemes
(e.g. JPEG, MPEG)

Sparse approximations



JPEG
⇒



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Computing approximation fast

Basic approach:

- ▶ FFT computes \hat{x} from x in $O(n \log n)$ time
- ▶ compute top k coefficients in $O(n)$ time.

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Sparse FFT:

- ▶ directly computes k largest coefficients of \hat{x} (approximately – formal def later)
- ▶ Running time $O(k \log^2 n)$ or faster
- ▶ Sublinear time!

Sample complexity

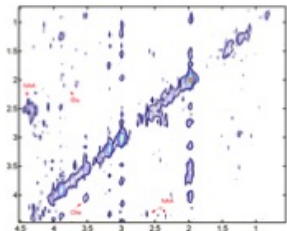
Besides runtime, other efficiency measures are important in some settings

In **medical imaging** (MRI, NMR), one measures Fourier coefficients \hat{x} of imaged object x (which is often sparse)

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Sample complexity

Sample complexity=number of samples accessed in time domain.

Governs the measurement complexity of imaging process.

Measure $\hat{x} \in \mathbb{C}^n$, compute the **Inverse** Discrete Fourier Transform (**IDFT**) of \hat{x} :

$$x_i = \sum_{j \in [n]} \hat{x}_j \cdot \omega^{ij}.$$

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Given access to signal x in time domain, find best k -sparse approximation to \hat{x} approximately

Minimize

1. runtime
2. number of samples

Algorithms

- ▶ Randomization
- ▶ Approximation
- ▶ Hashing
- ▶ Sketching
- ▶ ...

Signal processing

- ▶ Fourier transform
- ▶ Hadamard transform
- ▶ Filters
- ▶ Compressive sensing
- ▶ ...

- ▶ Lecture 1: summary of techniques from
Gilbert-Guha-Indyk-Muthukrishnan-Strauss'02, Akavia-Goldwasser-Safra'03,
Gilbert-Muthukrishnan-Strauss'05, Iwen'10, Akavia'10,
Hassanieh-Indyk-Katabi-Price'12a, Hassanieh-Indyk-Katabi-Price'12b
- ▶ Lecture 2: Algorithm with $O(k \log^2 n)$ runtime
Hassanieh-Indyk-Katabi-Price'12b
- ▶ Lecture 3: Algorithm with $O(k \log n)$ sample complexity
Indyk-K.-Price'14, Indyk-K.'14

Outline

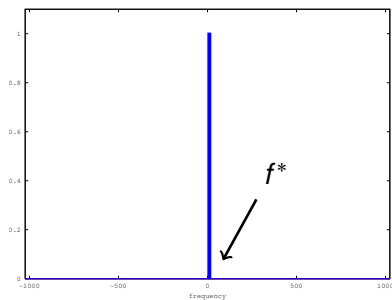
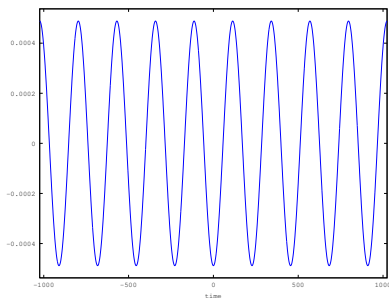
1. Computing Fourier transform of 1-sparse signals fast
2. Sparsity $k > 1$: main ideas and challenges

Outline

1. **Computing Fourier transform of 1-sparse signals fast**
2. Sparsity $k > 1$: main ideas and challenges

Sparse Fourier Transform ($k = 1$)

Warmup: \hat{x} is **exactly 1-sparse**: $\hat{x}_f = 0$ when $f \neq f^*$ for some f^*



Note: signal is a **pure frequency**

Given: access to x

Need: find f^* and \hat{x}_{f^*}

Two-point sampling

Input signal x is a pure frequency, so $x_j = \mathbf{a} \cdot \omega^{f^* \cdot j}$

Sample x_0, x_1

Two-point sampling

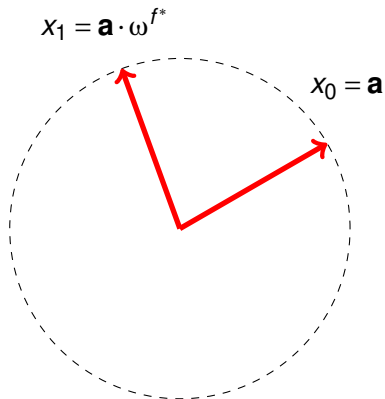
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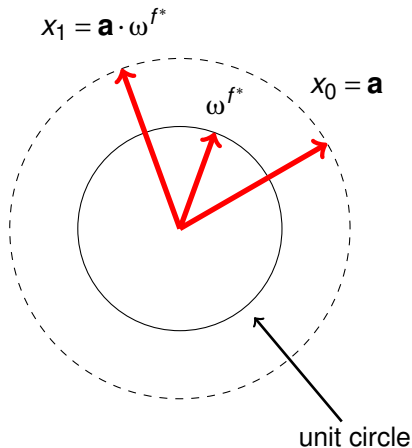
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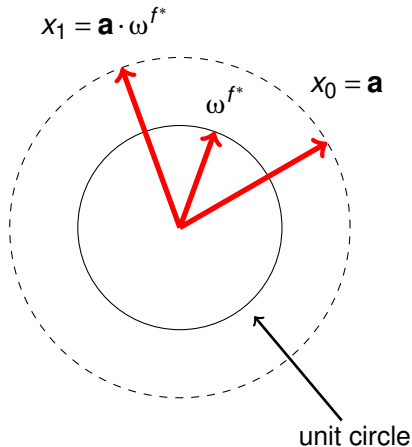
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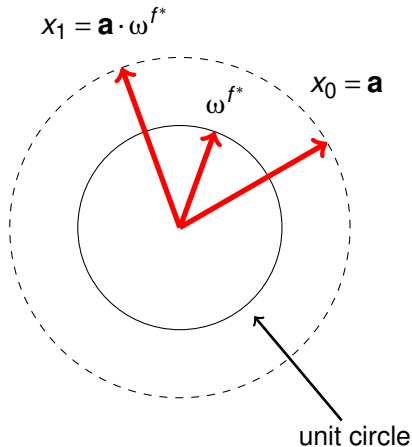
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Pro: constant time algorithm

Con: depends heavily on the signal being pure



Two-point sampling

Input signal x is a pure frequency + noise, so $x_j = \mathbf{a} \cdot \omega^{f^* \cdot j} + \text{noise}$

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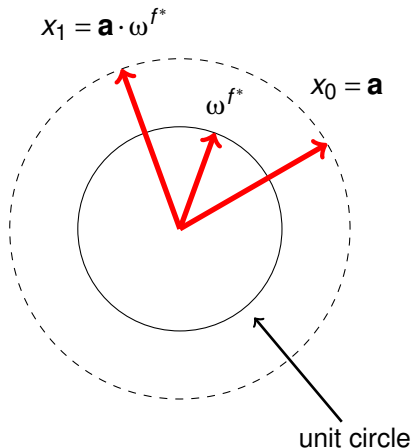
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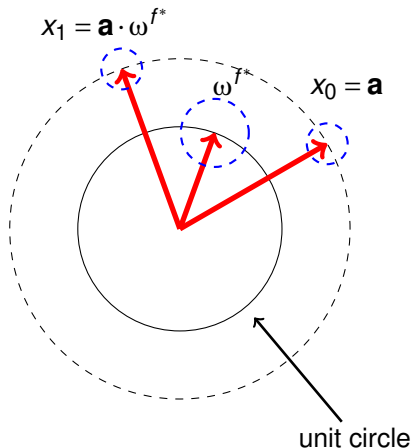
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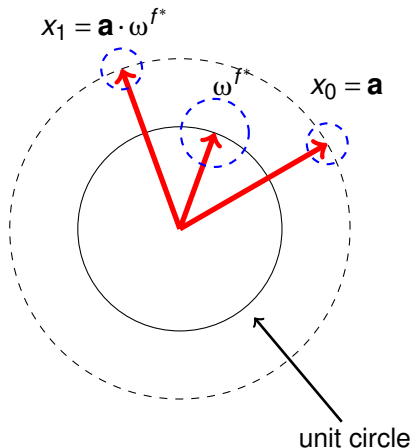
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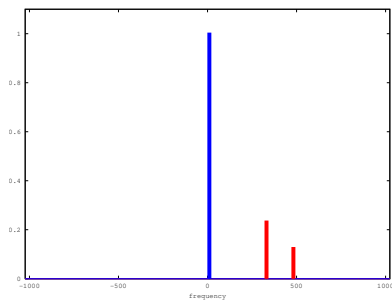
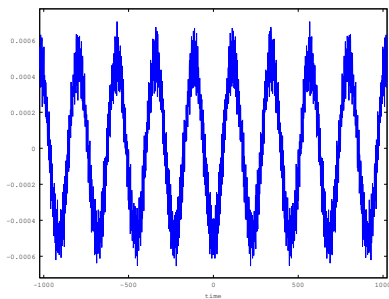


Pro: constant time algorithm

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Sparse Fourier Transform ($k = 1$)

Warmup – part 2: \hat{x} is 1-sparse plus noise



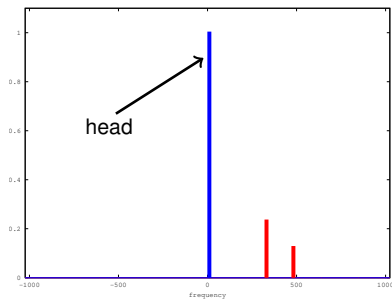
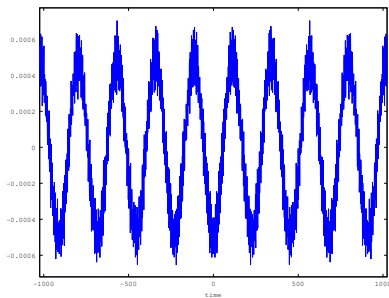
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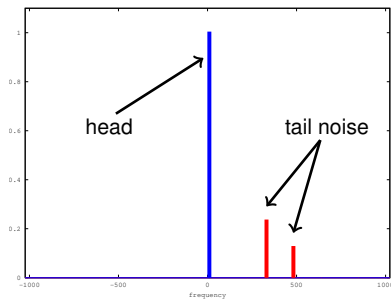
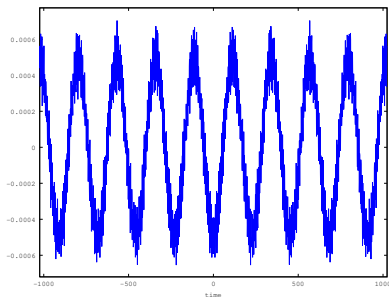
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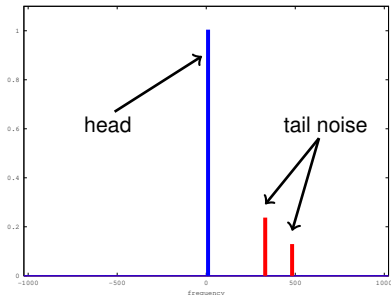
Ideally, find 1-sparse \hat{x}_{OPT} containing **largest frequency** of \hat{x}

Need to allow approximation: find \hat{y} such that

$$\|\hat{x} - \hat{y}\|_2 \leq C \cdot \|\hat{x} - \hat{x}_{OPT}\|_2$$

where $C > 1$ is the approximation factor.

(This is the l_2/l_2 guarantee)



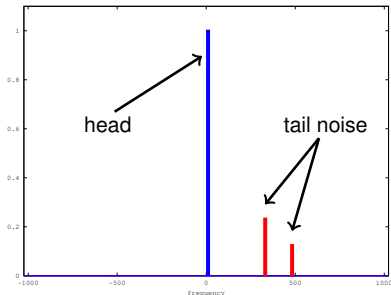
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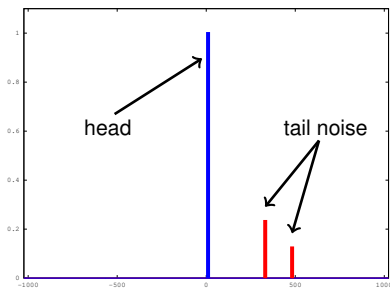
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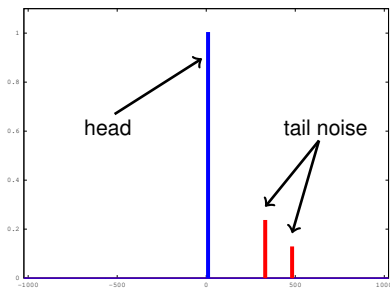
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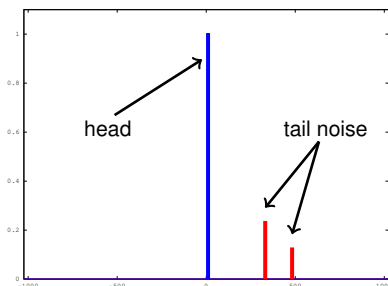
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Note: only meaningful if

$$\|\hat{x} - \hat{y}\|_2 > C \|\hat{x} - \hat{x}_{OPT}\|_2$$

or, equivalently,

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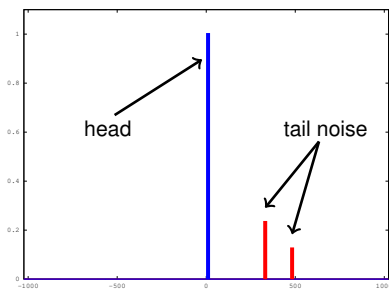
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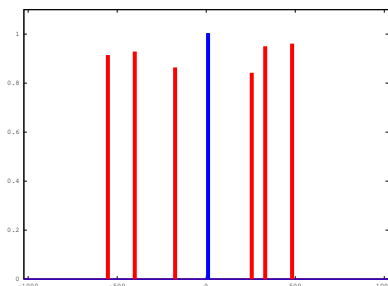
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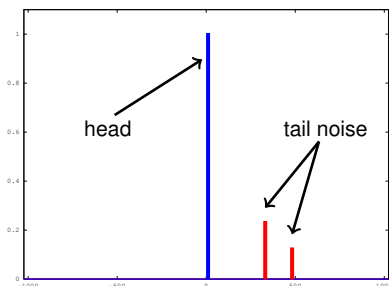
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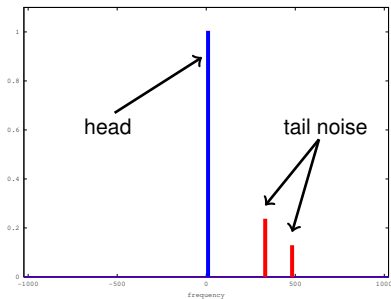
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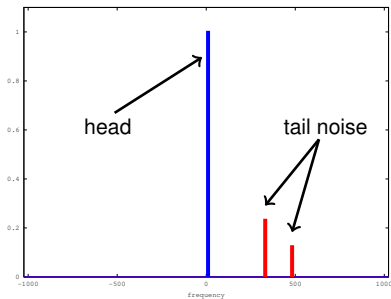
A robust algorithm for finding the heavy hitter



Describe algorithm for the noiseless case first ($\epsilon = 0$)

Suppose that $x_j = \mathbf{a} \cdot \omega^{f^* \cdot j}$.

A robust algorithm for finding the heavy hitter



Describe algorithm for the noiseless case first ($\epsilon = 0$)

Suppose that $x_j = \mathbf{a} \cdot \omega^{f^* \cdot j}$.

Will find f^* bit by bit (binary search).

Bit 0

Suppose that $f^* = 2f + b$, we want b

Compute

- ▶ $x_0 = \mathbf{a}$
- ▶ $x_{n/2} = \mathbf{a} \cdot \omega^{f^* \cdot (n/2)}$

Claim

For all $r \in [n]$ we have

$$x_{n/2} = x_0 \cdot (-1)^b$$

(Even frequencies are $n/2$ -periodic, odd are $n/2$ -antiperiodic)

Proof.

$$x_{n/2} = \mathbf{a} \cdot \omega^{f^* (n/2)} = \mathbf{a} \cdot (-1)^{2f+b} = x_0 \cdot (-1)^b$$



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- ▶ $x_{0+r} = \mathbf{a} \cdot \omega^{\mathbf{f}^*r}$
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Will need arbitrary r 's for the noisy setting

Bit 0 test

Set $b_0 \leftarrow 0$ if $|x_{n/2+r} + x_r| > |x_{n/2+r} - x_r|$

$b_0 \leftarrow 1$ o.w.

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Correctness:

If $b = 0$, then $|x_{n/2+r} + x_r| = 2|x_r| = 2|a|$

and $|x_{n/2+r} - x_r| = 0$

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If $b = 1$, then $|x_{n/2+r} + x_r| = 0$

and $|x_{n/2+r} - x_r| = 2|x_r| = 2|\mathbf{a}|$

Bit 1

Can pretend that $b_0 = 0$. Why?

Claim (Time shift theorem)

If $y_j = x_j \cdot \omega^{j \cdot \Delta}$, then $\hat{y}_f = \hat{x}_{f-\Delta}$.

Proof.

$$\begin{aligned}\hat{y}_f &= \frac{1}{n} \sum_{j \in [n]} y_j \cdot \omega^{-fj} = \frac{1}{n} \sum_{j \in [n]} x_j \cdot \omega^{j \cdot \Delta} \cdot \omega^{-fj} \\ &= \frac{1}{n} \sum_{j \in [n]} x_j \cdot \omega^{-j \cdot (f-\Delta)} \\ &= \hat{x}_{f-\Delta}\end{aligned}$$



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If $y_j = x_j \cdot \omega^{j \cdot \Delta}$, then $\hat{y}_f = \hat{x}_{f-\Delta}$.

Proof.

$$\begin{aligned}\hat{y}_f &= \frac{1}{n} \sum_{j \in [n]} y_j \cdot \omega^{-fj} = \frac{1}{n} \sum_{j \in [n]} x_j \cdot \omega^{j \cdot \Delta} \cdot \omega^{-fj} \\ &= \frac{1}{n} \sum_{j \in [n]} x_j \cdot \omega^{-j \cdot (f-\Delta)} \\ &= \hat{x}_{f-\Delta}\end{aligned}$$

□

If $b_0 = 1$, then replace x with $y_j := x_j \cdot \omega^{j \cdot b_0}$.

Bit 1

Assume $b_0 = 0$. Then we have $f^* = 2f$, so

$$x_j = \mathbf{a} \cdot \omega^{f^*j} = \mathbf{a} \cdot \omega^{2f \cdot j} = \mathbf{a} \cdot \omega^{\frac{f \cdot j}{N/2}}.$$

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Decoding bit by bit

Set $b_0 \leftarrow 0$ if $|x_{n/2+r} + x_r| > |x_{n/2+r} - x_r|$

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Overall: $O(\log n)$ samples to identify f^* . Runtime $O(\log n)$

Noisy setting (dealing with ε)

We now have

$$\begin{aligned}x_j &= \mathbf{a} \cdot \omega^{f^* \cdot j} + \sum_{f \neq f^*} \hat{\chi}_f \omega^{fj} \\ &= \mathbf{a} \cdot \omega^{f^* \cdot j} + \mu_j \quad (\mu_j \text{ is the noise in time domain})\end{aligned}$$

Argue that μ_j is usually small?

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So **on average** $|\mu_j|^2$ is small:

$$\mathbf{E}_j[|\mu_j|^2] \leq \sum_{f \neq f^*} |\hat{\chi}_f|^2 \leq \epsilon |\mathbf{a}|^2$$

Need to ensure that:

1. f^* is decoded correctly
2. \mathbf{a} is estimated well enough to satisfy ℓ_2/ℓ_2 guarantees:

$$\|\hat{\mathbf{x}} - \hat{\mathbf{y}}\|_2 \leq C \cdot \|\hat{\mathbf{x}} - \hat{\mathbf{x}}_{OPT}\|_2$$

Decoding in the noisy setting

Bit 0: set $b_0 \leftarrow 0$ if $|x_{n/2+r} + x_r| > |x_{n/2+r} - x_r|$ and $b_0 \leftarrow 1$ o.w.

Claim

If $\mu_{n/2+r} < |a|/2$ and $\mu_r < |a|/2$, then outcome of the bit test is the same.

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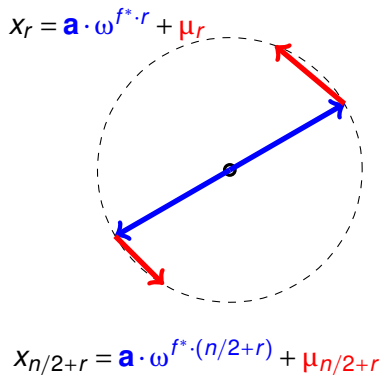
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On average $|\mu_j|^2$ is small:

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By Markov's inequality

$$\mathbf{Pr}_j[|\mu_j|^2 > |\mathbf{a}|^2/4] \leq \mathbf{Pr}_j[|\mu_j|^2 > (\mathbf{1}/(4\varepsilon)) \cdot \mathbf{E}_j[|\mu_j|^2]] \leq 4\varepsilon$$

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$$\mathbf{Pr}_r[|\mu_r| \leq |\mathbf{a}|/2 \text{ and } |\mu_{n/2+r}| \leq |\mathbf{a}|/2] \geq 1 - 8\epsilon$$

Thus, a bit test is correct with probability at least $1 - 8\epsilon$.

Decoding in the noisy setting

Bit 0: set b_0 to zero if

$$|x_{n/2+r} + x_r| > |x_{n/2+r} - x_r|$$

and to 1 otherwise

For $\epsilon < 1/64$ each test is correct with probability $\geq 3/4$.

Final test: perform $T \gg 1$ independent tests, use majority vote.

How large should T be? Success probability?

Decoding in the noisy setting

For $j = 1, \dots, T$ let

$$Z_j = \begin{cases} 1 & \text{if } j\text{-th test is correct} \\ 0 & \text{o.w.} \end{cases}$$

We have $\mathbf{E}[Z_j] \geq 3/4$.

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Chernoff bounds

$$\Pr\left[\sum_{j=1}^T Z_j < T/2\right] < e^{-\Omega(T)}.$$

Set $T = O(\log \log n)$

Majority is correct with probability at least $1 - 1/(16 \log_2 n)$

So all bits correct with probability $\geq 15/16$

Estimating the value of heavy hitter

Recall that

$$x_r = \mathbf{a} \cdot \omega^{f^* \cdot r} + \mu_r \quad (\text{noise})$$

Our estimate: pick random $r \in [n]$ and output

$$\text{est} \leftarrow \mathbf{x}_r \omega^{-f^* \cdot r}$$

Expected squared error?

$$\mathbf{E}_r[|\text{est} - \mathbf{a}|^2]$$

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Now by Markov's inequality

$$\Pr_r[|\text{est} - \mathbf{a}|^2 > 4\epsilon |\mathbf{a}|^2] < 1/4.$$

Putting it together: algorithm for 1-sparse signals

Let

$$\hat{y}_f = \begin{cases} \text{est} & \text{if } f = f^* \\ 0 & \text{o.w.} \end{cases}$$

By triangle inequality

$$\begin{aligned} \|\hat{y} - \hat{x}\|_2 &\leq \|\hat{y}_{f^*} - \mathbf{a}\|_2 + \|\hat{y}_{-f^*} - \hat{x}_{-f^*}\|_2 \\ &\leq 2\sqrt{\epsilon}|\mathbf{a}| + \sqrt{\epsilon}|\mathbf{a}| \\ &= 3\|\hat{x} - \hat{x}_{OPT}\|_2. \end{aligned}$$

Thus, with probability $\geq 2/3$ our algorithm satisfies ℓ_2/ℓ_2 guarantee with $C = 3$.

Runtime= $O(\log n \log \log n)$

Sample complexity= $O(\log n \log \log n)$

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What about $k > 1$

Outline

1. Sparsity: definitions, motivation
2. Computing Fourier transform of 1-sparse signals fast
3. **Sparsity $k > 1$: main ideas and challenges**

Sparsity $k > 1$

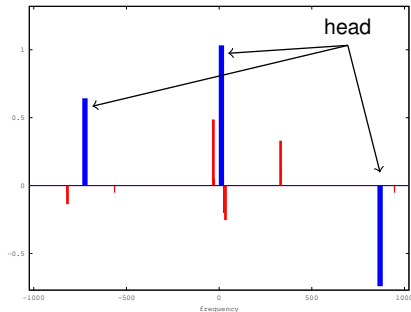
Let $\hat{x}_{OPT} \leftarrow$ best k -sparse approximation of \hat{x}

Our goal: find \hat{y} such that

$$\|\hat{x} - \hat{y}\|_2 \leq C \cdot \|\hat{x} - \hat{x}_{OPT}\|_2$$

where $C > 1$ is the approximation factor.

(This is the l_2/l_2 guarantee)



Sparsity $k > 1$

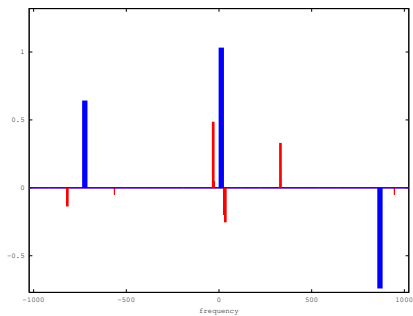
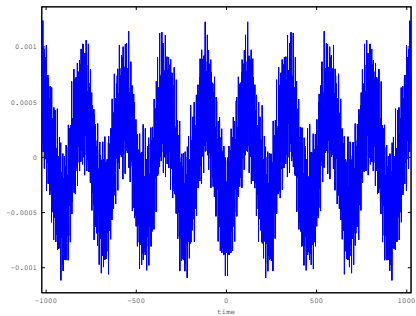
Main idea: implement hashing to reduce to 1-sparse case:

- ▶ 'hash' frequencies into $\approx k$ bins
- ▶ run 1-sparse algo on isolated elements

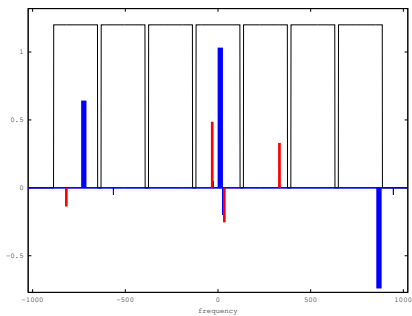
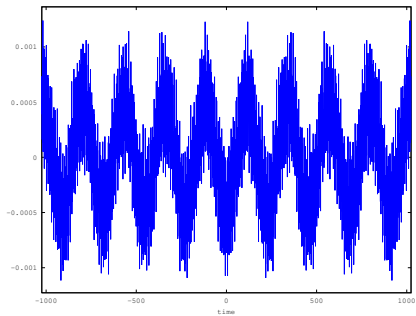
Assumption: can randomly permute frequencies (will remove in next lecture)

Implement hashing? Need to design a bucketing scheme for the frequency domain

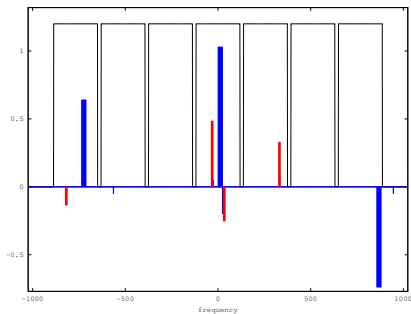
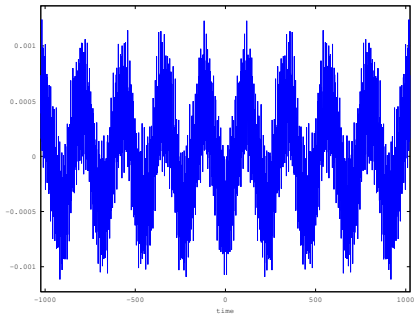
Partition frequency domain into $B \approx k$ buckets



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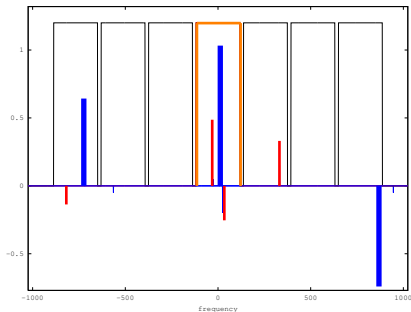
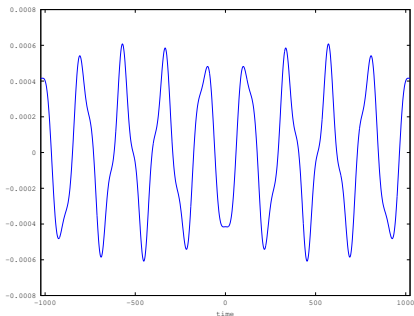


For each $j = 0, \dots, B-1$ let

$$\hat{u}_f^j = \begin{cases} \hat{x}_f, & \text{if } f \in j\text{-th bucket} \\ 0 & \text{o.w.} \end{cases}$$

Restricted to a bucket, signal is likely **approximately 1-sparse!**

Partition frequency domain into $B \approx k$ buckets

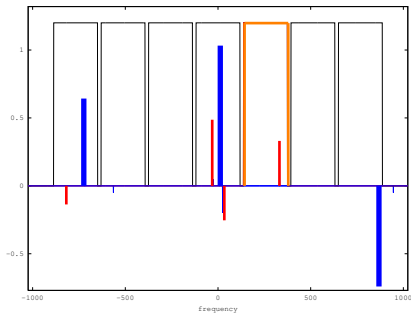
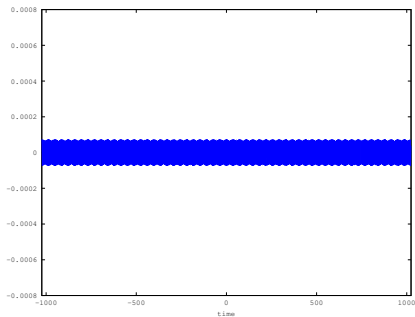


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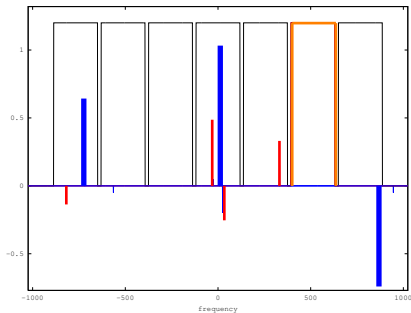
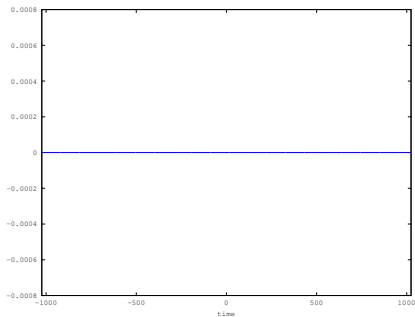


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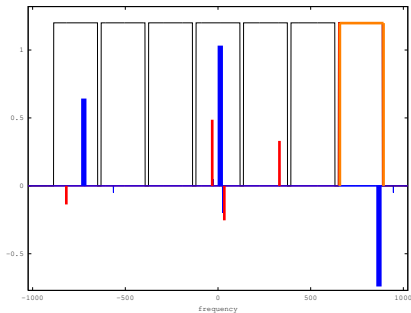
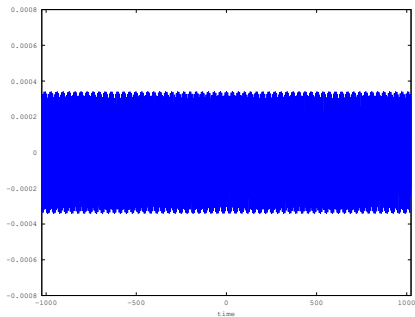


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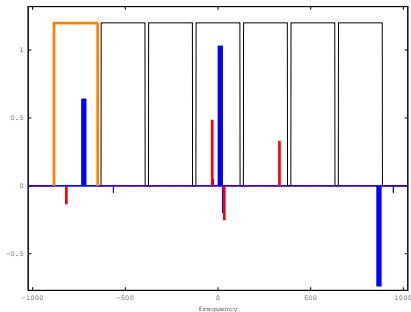
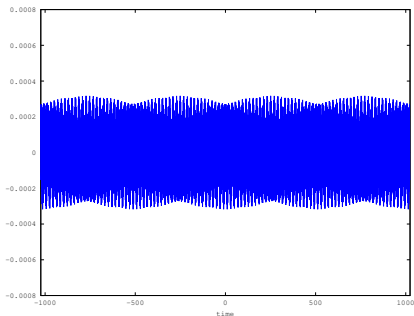


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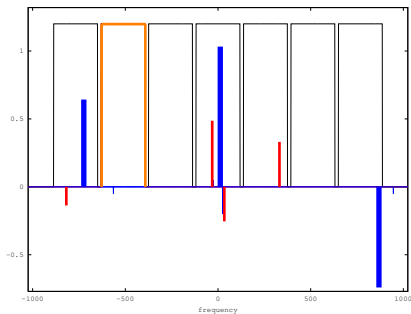
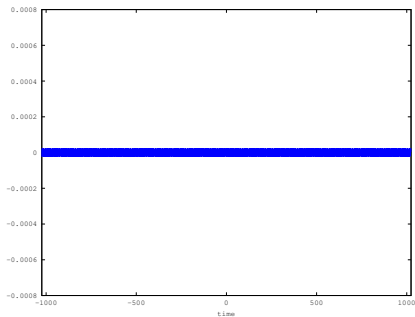


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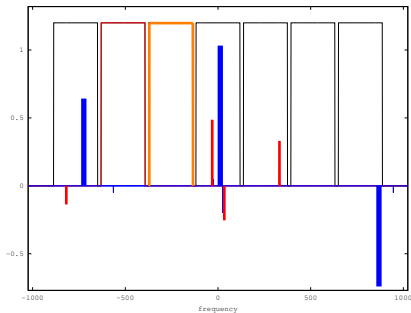
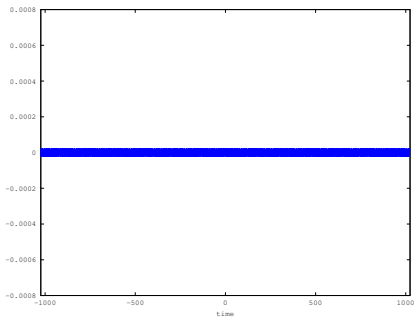


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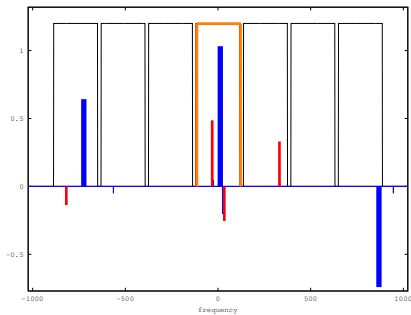
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Restricted to a bucket, signal is likely **approximately 1-sparse!**

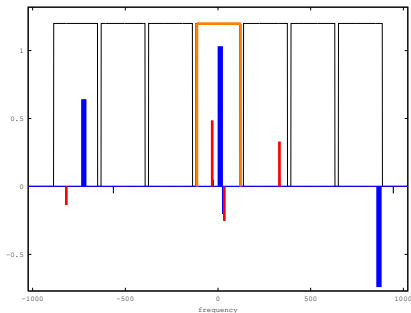
Zero-th bucket signal u^0 :

$$\hat{u}_f^0 = \begin{cases} \hat{X}_f, & \text{if } f \in \left[-\frac{n}{2B} : \frac{n}{2B}\right] \\ 0 & \text{o.w.} \end{cases}$$



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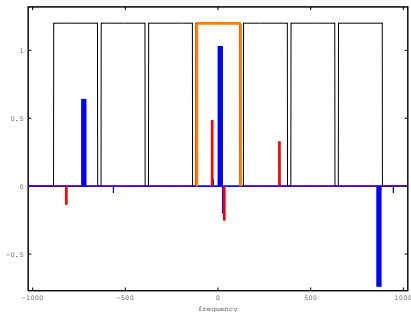


We want time domain access to u^0 : for any $a = 0, \dots, n-1$, compute

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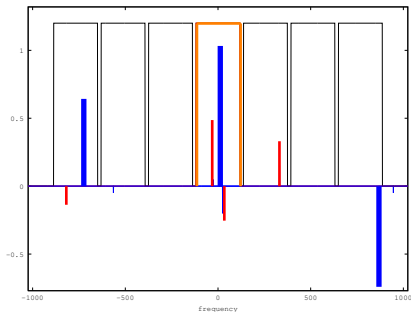


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where $y_j = x_{j+a}$ (y is a time shift of x by the **time shift theorem**).

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$$\hat{G}_f = \begin{cases} 1, & \text{if } f \in \left[-\frac{n}{2B} : \frac{n}{2B}\right] \\ 0 & \text{o.w.} \end{cases}$$

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Need to evaluate

$$(\hat{x} * \hat{G})\left(\mathbf{j} \cdot \frac{\mathbf{n}}{\mathbf{B}}\right)$$

for $j = 0, \dots, B - 1$.

We have access to x , not \hat{x} ...

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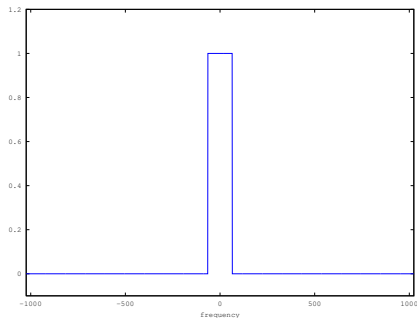
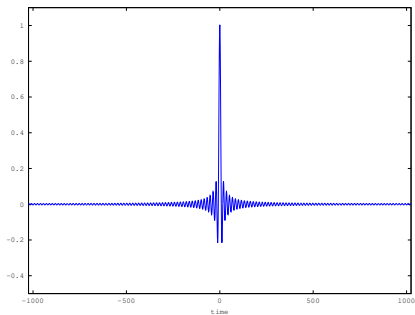
Suffices to compute

$$\widehat{x \cdot G}_{j \cdot \frac{n}{B}}, j = 0, \dots, B-1$$

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$$\widehat{x} \cdot \widehat{G}_{j, \frac{n}{B}}, j = -B/2, \dots, B/2 - 1$$

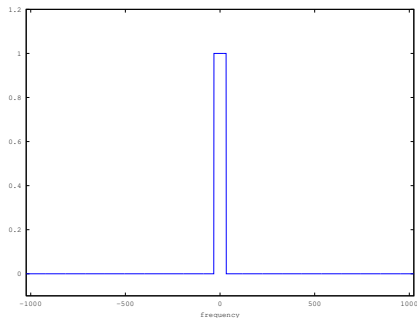
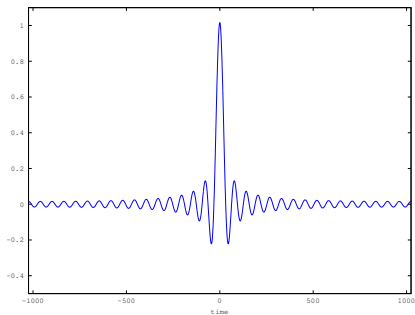
Sample complexity? Runtime?



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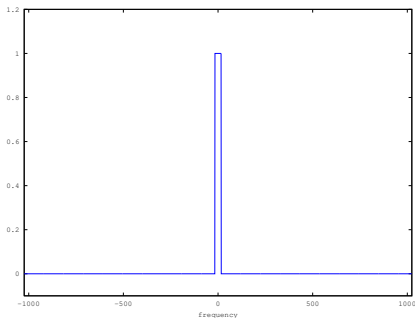
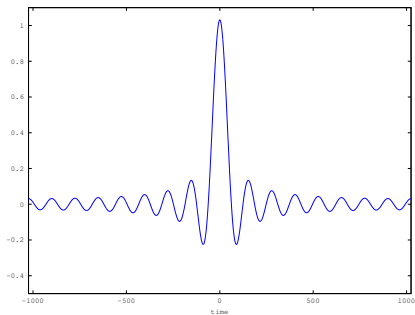
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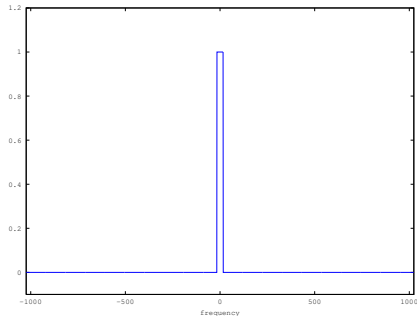
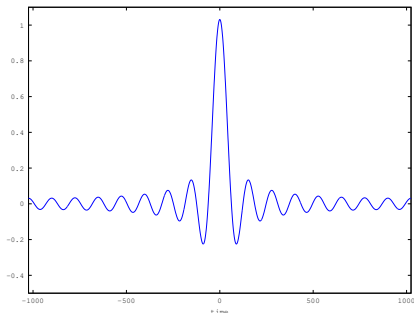
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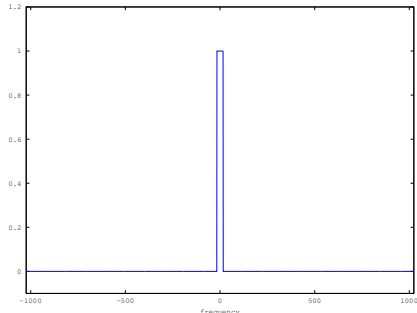
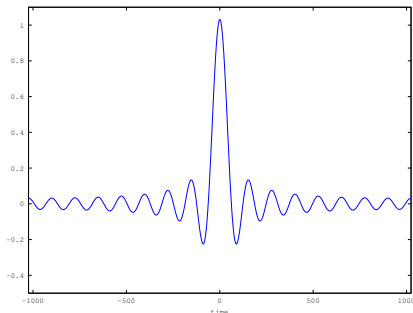


Computing $x \cdot G$ takes $\Omega(N)$ time and samples!

Suffices to compute

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Sample complexity? Runtime?



Computing $x \cdot G$ takes $\Omega(N)$ time and samples!

Design a filter $\text{supp}(G) \approx k$? Truncate sinc? Tolerate imprecise hashing? Collisions in buckets?