# Sparse Fourier Transform (lecture 3)

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In last lecture:

1-sparse noiseless case: two-point sampling

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- 1-sparse noisy case: O(log nloglog n) time and samples
- reduction from k-sparse to 1-sparse case, via filtering











For each  $j = 0, \dots, B - 1$  let

 $\widehat{u}_{f}^{j} = \begin{cases} \widehat{x}_{f}, & \text{if } f \in j\text{-th bucket} \\ 0 & \text{o.w.} \end{cases}$ 



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$$U_{a}^{0} = \sum_{-\frac{n}{2B} \le f \le \frac{n}{2B}} \widehat{X}_{f} \cdot \omega^{f \cdot a}.$$

Let

$$\widehat{G}_f = \begin{cases} 1, & \text{if } f \in \left[-\frac{n}{2B} : \frac{n}{2B}\right] \\ 0 & \text{o.w.} \end{cases}$$

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Reducing k-sparse recovery to 1-sparse recovery

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### Sample complexity? Runtime?



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To sample all signals  $u^{j}$ , j = 0, ..., B - 1 in time domain, it suffices to compute

$$\widehat{x \cdot G_{j \cdot \frac{n}{B}}}, j = 0, \dots, B-1$$



Computing  $x \cdot G$  takes supp(G) samples.

Design *G* with supp(*G*)  $\approx$  *k* that approximates rectangular filter?

Last lecture: designed G with  $supp(G) = O(k \log N)$  that approximates rectangular filter In this lecture:

- recovery algorithm (k-sparse noiseless case)
- recovery algorithm (k-sparse noisy case)

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### 1. Basic block: partial recovery

2. Full algorithm

### **Basic block**

Assume

- n is a power of 2
- *x̂* contains at most *k* coefficients with polynomial precision (e.g. *x̂*<sub>f</sub> in {−*n*<sup>O(1)</sup>,...,*n*<sup>O(1)</sup>})

Then there exists an  $O(k \log n)$  time algorithm that

- outputs at most k potential coefficients
- outputs each nonzero  $\hat{x}_f$  correctly with probability at least  $1 \beta$  for a constant  $\beta > 0$



Let *G* be a  $(B, \delta/n, \gamma)$ -flat window function:

- B buckets
- flat region of width 1 γ
- leakage  $\leq \delta/n = 1/n^{O(1)}$

Such G can be constructed with

 $\operatorname{supp}(G) = O((k/\gamma)\log n)$ 

## PARTIALRECOVERY - algorithm

Main idea: filter, then run 1-sparse algorithm on each subproblem

PARTIAL RECOVERY  $(x, B, \gamma, \delta)$ 

Choose random  $b \in [n]$  and odd  $\sigma \in \{1, 2, ..., n\}$ 

Define 
$$x'_{j} \leftarrow x_{\sigma j} \omega^{jo}$$
  
 $x''_{j} \leftarrow x'_{j+1}$   
Compute  $\widehat{c}'_{j \cdot \frac{n}{B}}, j \in [B]$ , where  $c' = x' \cdot G$   
 $\widehat{c}''_{j \cdot \frac{n}{B}}, j \in [B]$ , where  $c'' = x'' \cdot G$ 

••

Run 1-sparse decoding one  $\hat{c}', \hat{c}''$ 

## PARTIALRECOVERY - algorithm

Recovering 5-sparse signal  $\hat{x}$  from measurements of x



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For  $j \in [B]$ If  $|\widehat{c}'_{j \cdot n/B}| > 1/2$ Decode from  $\widehat{c}'_{j \cdot n/B}, \widehat{c}''_{j \cdot n/B}$ (Two-point sampling) End End

Claim

For each  $u \in supp(\hat{x})$  the probability that u is not reported is bounded by  $O(k/B + \gamma)$ .

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# Computing $\widehat{c}_{j \cdot n/B}$

**Option 1** – directly compute FFT of  $(x \cdot G)_{-T}, ..., (x \cdot G)_{T}$ ,  $T = O((k/\gamma) \log n)$ 

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- Computes too many samples of  $\hat{x} * \hat{G}$
- **Option 2** alias  $x \cdot G$  to B bins first
  - Compute

$$b_i = \sum_{j \in [n/B]} x_{i+j \cdot B} G_{i+j \cdot B}$$

Compute FFT of b in time

$$O(B\log B) = O((k/\gamma)\log n)$$

- 1. Basic block: partial recovery
- 2. Full algorithm

Let C > 0 be a sufficiently large constant.

PARTIAL RECOVERY  $(x, C \cdot k, \frac{1}{16}, 1/\text{poly}(n))$ 

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## Modified PARTIALRECOVERY

PARTIALRECOVERY( $B, \alpha, List$ )

Choose random *b*, odd  $\sigma$ 

Define  $x'_i = x_{\sigma j} \omega^{jb}$  $X_{i}^{\prime\prime} = X_{i+1}^{\prime}$ Compute  $\hat{c}'_{i,\frac{n}{2}}$ ,  $j \in [B]$ , where  $c' = x' \cdot G$  $\widehat{c}_{i,\frac{n}{2}}^{\prime\prime}, j \in [B]$ , where  $c^{\prime\prime} = x^{\prime\prime} \cdot G$ **For** *j* ∈ [*B*] If  $|\hat{c}'_{i\cdot n/B}| > 1/2$ Decode from  $\hat{c}'_{j\cdot n/B}, \hat{c}''_{j\cdot n/B}$ (Two-point sampling) End End

### PARTIAL RECOVERY – updating the bins

Previously located elements are still in the signal...

Subtract recovered elements from the bins




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# Full algorithm

List  $\leftarrow \phi$ For t = 0 to  $\log k$   $B_t \leftarrow Ck/4^t$   $\triangleright$  # of buckets to hash to  $\gamma_t \leftarrow 1/(C2^t)$   $\triangleright$  sharpness of filter List  $\leftarrow$  List + PARTIALRECOVERY( $B_t, \gamma_t, List$ ) End

#### Full algorithm – analysis Let

 $\hat{e}_t \leftarrow \text{contents of the list after stage } t.$ 

Define 'good event'  $\mathcal{E}_t$  as

$$\mathscr{E}_t := \left\{ ||\widehat{x} - \widehat{e}_t||_0 \le k/8^t \right\}$$

Conditional on  $\mathcal{E}_{t-1}$ , for every  $f \in [n]$  the probability of failure to recover is at most the sum of

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probability of collision with another element, which is no more than

$$\frac{k/8^t}{B_t} = \frac{k/8^t}{C \cdot k/4^t} \le \frac{1}{C \cdot 2^t}$$

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probability of collision with another element, which is no more than

$$\frac{k/8^t}{B_t} = \frac{k/8^t}{C \cdot k/4^t} \le \frac{1}{C \cdot 2^t}$$

probability of being hashed to the non-flat region, which is no more than

$$O(\gamma_t) = O\left(\frac{1}{C2^t}\right)$$

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Then

 $\mathbf{Pr}[\mathscr{E}_t | \mathscr{E}_{t-1}] \leq \mathbf{Pr}[\text{fraction of failures is} \geq 1/8 | \mathscr{E}_{t-1}] \leq O\left(\frac{1}{C \cdot 2^t}\right)$ 

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So for a sufficiently large C > 0

$$\mathbf{Pr}[\overline{\mathscr{E}}_1 \vee \ldots \vee \overline{\mathscr{E}}_{\log k}] \le O(1/C) \cdot (1/2 + 1/4 + \ldots) = O(1/C) < 1/10$$

# Full algorithm – analysis

List 
$$\leftarrow \emptyset$$
  
For  $t = 1$  to  $\log k$   
 $B_t \leftarrow Ck/4^t$   
 $\gamma_t \leftarrow 1/(C2^t)$   
List  $\leftarrow List + PARTIALRECOVERY(B_t, \gamma_t, List)$   
End

Time complexity

- ► DFT: O(k log n) + O((k/4) log n) + ... = O(k log n)
- List update: k · log n

# Sample complexity

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Sample complexity  $O(k \log n) + O((k/4) \log n) + ... = O(k \log n)$ 

**Suboptimal:** sufficient to measure  $x_0, x_1, ..., x_{2k}$  to reconstruct  $\hat{x}$  if supp $(\hat{x}) \le k$  (exercise).

Next:

recovery in the noisy setting

$$||\widehat{x} - \widehat{y}||^2 \le C \cdot \min_{k-\text{sparse }\widehat{z}} ||\widehat{x} - \widehat{z}||^2$$



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$$\begin{aligned} |\widehat{x}_1| \geq \ldots \geq |\widehat{x}_k| \geq \\ |\widehat{x}_{k+1}| \geq |\widehat{x}_{k+2}| \geq \ldots \end{aligned}$$

$$\operatorname{Err}_{k}^{2}(\widehat{x}) = \sum_{j=k+1}^{n} |\widehat{x}_{j}|^{2}$$

Residual error bounded by noise energy  $\operatorname{Err}_k^2(\hat{x})$ 



$$||\widehat{x} - \widehat{y}||^2 \le C \cdot \operatorname{Err}_k^2(\widehat{x})$$

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Residual error bounded by noise energy  $\operatorname{Err}_{k}^{2}(\hat{x})$ 





Sufficient to ensure that most elements are below average noise level:

$$|\widehat{x}_i - \widehat{y}_i|^2 \le c \cdot \operatorname{Err}_k^2(\widehat{x})/k =: \mu^2$$



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## Basic block (noiseless setting)

Assume

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Then there exists an  $O(k \log n)$  time algorithm that

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- n is a power of 2
- ➤ x̂ contains at most k coefficients with polynomial precision (e.g. x̂<sub>f</sub> in {-n<sup>O(1)</sup>,...,n<sup>O(1)</sup>}), plus noise

Then there exists an  $O(k \log n)$  time algorithm that

- outputs at most k potential coefficients
- outputs each nonzero x̂<sub>f</sub> that is above noise level correctly with probability at least 1 − β for a constant β > 0



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Compute  $\widehat{c}'_{j \cdot \frac{n}{B}}, j \in [B]$ , where  $c' = x' \cdot G$   
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••

Run 1-sparse decoding one  $\hat{c}', \hat{c}''$ 

## PARTIALRECOVERY - algorithm

Recovering 5-sparse signal  $\hat{x}$  from measurements of x



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# PARTIALRECOVERY (noiseless setting)

Choose random  $b \in [n]$  and odd  $\sigma \in \{1, 2, ..., n\}$ 

Define  $x'_{j} \leftarrow x_{\sigma j} \omega^{jb}$   $x''_{j} \leftarrow x'_{j+1}$ Compute  $\widehat{c}'_{j \cdot \frac{n}{B}}, j \in [B]$ , where  $c' = x' \cdot G$   $\widehat{c}''_{j \cdot \frac{n}{B}}, j \in [B]$ , where  $c'' = x'' \cdot G$ For  $j \in [B]$ If  $|\widehat{c}'_{i \cdot n/B}| > 1/2$ 

If  $|\hat{c}'_{j\cdot n/B}| > 1/2$ Decode from  $\hat{c}'_{j\cdot n/B}, \hat{c}''_{j\cdot n/B}$ (Two-point sampling) End End

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Define 
$$x_j^{\mathbf{s},\mathbf{0},\mathbf{r}} \leftarrow x_{\sigma(j+\mathbf{r})} \omega^{(j+\mathbf{r})b}$$
  
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Compute  $(\widehat{x^{s,0,r} \cdot G})_{j \cdot n/B}$ , for  $j \in [B]$  $(\widehat{x^{s,1,r} \cdot G})_{j \cdot n/B}$ , for  $j \in [B]$ 

Initialize list  $L \leftarrow \emptyset$ 

**For** *j* ∈ [*B*]

Decode from  $\hat{x}_{j \cdot n/B}^{s,*,r}$ , add to list *L* (output *B* elements) (As in lecture 1)

#### End

Estimate values of  $i \in L$ , output top 3k

Suppose that *x* is approximately 1-sparse, i.e.

$$\sum_{f \neq f^*} |\widehat{x}_f|^2 \le \frac{\varepsilon}{\varepsilon} |\widehat{x}_{f^*}|^2 \quad \text{(small noise)}$$

for some small constant  $\epsilon$ .

Then

1. can find  $f^*$  using  $O(\log n \cdot \log \log n)$  runtime  $O(\log n \cdot \log \log n)$  samples with  $\ge 1 - 1/4$  success probability

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Need to ensure that noise is small in most subproblems

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Need to ensure that noise is small in most subproblems



For every head element  $i \in [k]$  and every tail element  $j \in [n] \setminus [k]$ **Pr**[*i* and *j* hash to the same bucket] = O(1/B)

Let 
$$\mu^2 := \frac{1}{k} \min_{k-\text{sparse } y} ||x-y||_2^2 = \frac{1}{k} \sum_{j=k+1}^n |x_j|^2$$
 (average noise level)

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So by Markov's inequality for every head element  $i \in [k]$ 

$$\Pr\left[\sum_{j\in[k+1:n] \text{ s.t. } \mathbf{h}(i)=\mathbf{h}(j)} |\widehat{x}_j|^2\right] > \varepsilon\mu^2] = O(k/(\varepsilon B))$$

### Basic block analysis (noiseless setting)

#### Claim

For each  $u \in supp(\hat{x})$  the probability that u is not reported is bounded by  $O(k/B + \gamma)$ .

- being mapped within n/B of another frequency is O(k/B)
- being mapped close to boundary of the bucket is O(y)



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Estimate values of  $i \in L$ , output top 3k

Given  $f^* \in [n]$ ,

1. can find  $w_{f^*}$  (estimate for  $\hat{x}_{f^*}$ ) in O(1) time and samples such that

$$|W_{f^*} - \widehat{x}_{f^*}|^2 \leq 3\varepsilon |\widehat{x}_{f^*}|^2$$

with probability 1 - 1/100

Given  $f^* \in [n]$ ,

1. can find  $w_{f^*}$  (estimate for  $\hat{x}_{f^*}$ ) in O(t) time and samples such that

$$|W_{f^*} - \widehat{x}_{f^*}|^2 \leq 3\varepsilon |\widehat{x}_{f^*}|^2$$

with probability  $1 - 2^{-t}$ 

Given  $f^* \in [n]$ ,

1. can find  $w_{f^*}$  (estimate for  $\hat{x}_{f^*}$ ) in  $O(\log n)$  time and samples such that

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with probability  $1 - 1/n^2$ 

Let *L* denote the list of located elements Using  $O(k \log^2 n)$  samples and runtime, can find  $w_l$  such that

 $|W_f - \widehat{X}_f|^2 \le 3\varepsilon |\widehat{X}_f|^2$ 

for all  $f \in L$ .

Let  $L' \subseteq L$  denote list of top 3k values in L (in terms of magnitude)

Let C > 0 be a sufficiently large constant.

PARTIAL RECOVERY  $(x, C \cdot k, \frac{1}{16}, 1/\text{poly}(n))$ 

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. . .

Let C > 0 be a sufficiently large constant.

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Permute spectrum

- Hash to 8 buckets
- Recover well-hashed coeffs
- Permute spectrum
- Hash to 4 buckets

. . .



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# Full algorithm

List  $\leftarrow \phi$ For t = 1 to  $\log k$   $B_t \leftarrow Ck/4^t$   $\gamma_t \leftarrow 1/(C2^t)$ List  $\leftarrow List + PARTIALRECOVERY(B_t, \gamma_t, List)$ End

### Time complexity:

- ► DFT:  $O(k \log^2 n(\log \log n)) + O((k/4) \log^2 n \log \log n) + ... = O(k \log^2 n \log \log n)$
- List update: k · log n

## Sample complexity

List  $\leftarrow \emptyset$ For t = 1 to  $\log k$   $B_t \leftarrow Ck/4^t$   $\gamma_t \leftarrow 1/(C2^t)$ List  $\leftarrow List + PARTIALRECOVERY(B_t, \gamma_t, List)$ End

Sample complexity:  $O(k \log^2 n(\log \log n)) + O((k/4) \log^2 n(\log \log n)) + ... = O(k \log^2 n \log \log n)$ 

Suboptimal (?): a lower bound of  $\Omega(k \log(n/k))$  known

### Runtime and sample complexity

Noisy: runtime  $O(k \log^2 n)$ , sample complexity  $O(k \log^2 n \log \log n)$ 

O(log log n) can be removed, see Hassanieh-Indyk-Katabi-Price'STOC12

Sample complexity lower bound:  $\Omega(k \log(n/k))$  (Do Ba, Indyk, Price, Woodruff'SODA10)

#### Next lecture:

```
O(k \log n (\log \log n)^{O(1)}) samples, O(k \log^2 n (\log \log n)^{O(1)}) runtime (Indyk-Kapralov-Price'SODA14)
```

and

 $O(k \log n)$  samples and  $O(n \log^3 n)$  runtime (Indyk-Kapralov'FOCS14)